"A Comment on Fast Three-Axis Attitude Determination Using Vector Observations and Inverse Iteration" (Technical Note), M. D. Shuster, *The Journal of the Astronautical Sciences*, Vol. 31, No. 4, October–December 1983, pp. 579–584.

John L. Tietze claimed that the application of inverse iteration to Davenport's q-algorithm was faster than QUEST and avoided the need for sequential rotations to avoid the singularity. 1983d successfully disputed those claims.

Succeeded 1981a.